

1.2 Construction and Types of Ball Bearings

A ball bearing usually consists of four parts: an inner ring, an outer ring, the balls and the cage or separator. To increase the contact area and permit larger loads to be carried, the balls run in curvilinear grooves in the rings. The radius of the groove is slightly larger than the radius of the ball, and a very slight amount of radial play must be provided. The bearing is thus permitted to adjust itself to small amounts of angular misalignment between the assembled shaft and mounting. The separator keeps the balls evenly spaced and prevents them from touching each other on the sides where their relative velocities are the greatest.

Ball bearings are made in a wide variety of types and sizes. Single-row radial bearings are made in four series, extra light, light, medium, and heavy, for each bore, as illustrated in **Fig. 1-3(a)**, **(b)**, and **(c)**. The heavy series of bearings is designated by 400. Most, but not all, manufacturers use a numbering system so devised that if the last two digits are multiplied by 5, the result will be the bore in millimeters. The digit in the third place from the right indicates the series number. Thus, bearing 307 signifies a medium-series bearing of 35-mm bore. For additional digits, which may be present in the catalog number of a bearing, refer to manufacturer's details. Some makers list deep groove bearings and bearings with two rows of balls. For bearing designations of **Quality Bearings & Components (QBC)**, see special pages devoted to this purpose.

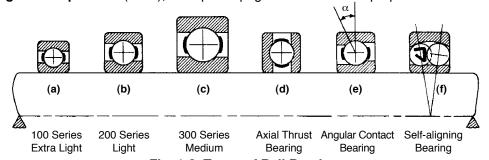


Fig. 1-3 Types of Ball Bearings

The radial bearing is able to carry a considerable amount of axial thrust. However, when the load is directed entirely along the axis, the thrust type of bearing should be used. The angular contact bearing will take care of both radial and axial loads. The selfaligning ball bearing will take care of large amounts of angular misalignment. An increase in radial capacity may be secured by using rings with deep grooves, or by employing a double-row radial bearing.

Radial bearings are divided into two general classes, depending on the method of assembly. These are the Conrad, or nonfilling-notch type, and the maximum, or filling-notch type. In the Conrad bearing, the balls are placed between the rings as shown in **Fig. 1-4(a)**. Then they are evenly spaced and the separator is riveted in place. In the maximum-type bearing, the balls are inserted through a filling notch ground into each ring, as shown in **Fig. 1-4(b)**. Because more balls can be

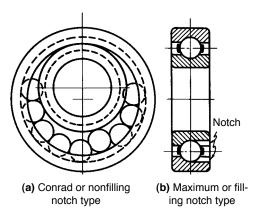


Fig. 1-4 Methods of Assembly for Ball Bearings