1.8 Roller Bearings

Several roller bearings are shown in Fig. 1-2 as well as in Fig. 1-11. These types of bearings are usually used when shock and impact loads are present, or when large bearings are needed.

A roller bearing, in general, consists of the same four elements as a ball bearing: the two rings, the cage, and the rollers. Some typical examples of roller bearings are shown in Fig. 1-11. Means of mounting roller bearings are shown in Fig. 1-12.

In a plain roller bearing, the flanges on the rings serve to guide the rollers in the proper direction. When the flanges are omitted from one of the rings, as shown in Fig. 1-11, the rings can then be displaced axially with respect to each other, and no thrust component can be carried.

In addition to the radial load, the tapered roller bearing can carry a large axial component whose magnitude depends on the angularity of the rollers. The radial load will also produce a thrust component. The outer ring is separable from the remainder of the bearing. In this type of
bearing, it is possible to make adjustment for the radial clearance. Two bearings are usually mounted opposed to each other, and the clearance is controlled by adjusting one bearing against the other. Double-row tapered roller bearings are also available.

Roller bearings in general can be applied only where the angular misalignment caused by shaft deflection is very slight. This deficiency is not present in the spherical roller bearing. It has excellent load capacity and can carry a thrust component in either direction.

In the helical roller bearing, the rollers are wound from strips of spring steel, and afterwards are hardened and ground to size. If desired, the rollers can bear directly on the shaft without an inner ring, particularly if the shaft surface has been locally hardened. This bearing has been successfully applied under conditions of dirty environment.

The needle bearing has rollers that are very long as compared to their diameters. Cages are frequently not used, and the inner ring may or may not be present. The outer ring may consist of hardened thin-walled metal as shown in Fig. 1-13; the housing in which the bearing is mounted must have sufficient thickness to give adequate support. The friction of needle bearings is several times as great as for ordinary cylindrical roller bearings. Because of the tendency of the unguided rollers to skew, needle bearings are particularly adapted to oscillating loads, as in wrist pins, rocker arms, and universal joints. For continuous rotation, needle bearings are usually suitable where the loading is intermittent and variable so that the needles will be frequently unloaded and thus tend to return to their proper locations. When the application involves angular misalignment of the shaft, two short bearings end to end usually are better than one bearing with long rollers. The needle bearing is low-priced and requires very little radial space.

Spherical roller bearings, Figures 1-12 and 1-13, can be used when the shaft has angular misalignment.

Thrust bearings can be constructed by the use of straight or tapered rollers.

Roller bearings are selected by a process similar to that used for ball bearings. They must be chosen, however, in accordance with the recommendations given in the catalog of the manufacturer of the particular type of bearing under consideration.

Roller bearings are usually made of case-hardened steels. The carburized case or exterior should have a hardness of 58-63 Rc. The core is softer with a hardness of 25-40 Rc. Certain plain-carbon and alloy steels have been found suitable for roller bearing service. The maximum temperature is limited to about 350° F.

The separator, cage, or retainer for conventional bearings is usually a stamping of low-carbon steel. For higher speeds or precision service, the separator is machined from a suitable copper alloy, such as bronze. Cages are also made of a solid lubricant material for use where